Assignment 4: Linear Functions Due Tuesday February 22, 2022

John McCuan

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Problem 1 (Axler 3A4) Let V and W be vector spaces over a field F.

- (a) What does it mean for a function $L: V \to W$ to be linear?
- (b) If $L: V \to W$ is linear and $\{v_1, v_2, \ldots, v_k\} \subset V$ with

 $\{Lv_1, Lv_2, \ldots, Lv_k\}$ linearly independent,

then show $\{v_1, v_2, \ldots, v_k\}$ is linearly independent.

Problem 2 (Axler 3A5) Let V and W be vector spaces over a field F.

- (a) If $L: V \to W$ is linear and $T: V \to W$ is linear, what is the sum of L and T?
- (b) If $L: V \to W$ is linear and $a \in F$, what is the scaling of L by a?
- (c) Denote by $\mathcal{L}(V \to W)$ the set of all linear functions from V to W. With the operations from parts (a) and (b) above prove $\mathcal{L}(V \to W)$ is a vector space. Hint: $\mathcal{L}(V \to W) \subset V^W$.

Problem 3 (Axler 3A3) Given real constants a_{1j} for j = 1, 2, ..., n, define a function $L : \mathbb{R}^n \to \mathbb{R}$ by

$$L(x_1, x_2, \dots, x_n) = \sum_{j=1}^n a_{1j} x_j.$$

- (a) Show that L is linear, i.e., $L \in \mathcal{L}(\mathbb{R}^n \to \mathbb{R})$.
- (b) What are the partial derivatives of L?
- (c) If $\{v_1, v_2, \ldots, v_n\}$ is a basis of \mathbb{R}^n and $T \in \mathcal{L}(\mathbb{R}^n \to \mathbb{R})$ satisfies

$$T(v_j) = L(v_j)$$
 for $j = 1, 2, ..., n$,

show T(v) = L(v) for all $v \in \mathbb{R}^n$, i.e., T = L.

Problem 4 (Axler 3A3) Given complex constants a_{1j} for j = 1, 2, ..., n, and

$$a_{2j}, for j = 1, 2, \dots, n,$$

define a function $L: \mathbb{R}^n \to \mathbb{R}^2$ by

$$L(x_1, x_2, \dots, x_n) = \left(\sum_{j=1}^n a_{1j} x_j, \sum_{j=1}^n a_{2j} x_j\right).$$

(a) Show that L is linear, i.e., $L \in \mathcal{L}(\mathbb{R}^n \to \mathbb{R}^2)$.

(b) If $T \in \mathcal{L}(\mathbb{R}^n \to \mathbb{R}^2)$, then show there are constants

$$b_{1j}$$
 for $j = 1, 2, \dots, n$ and b_{2j} for $j = 1, 2, \dots, n$

such that

$$T(x_1, x_2, \dots, x_n) = \left(\sum_{j=1}^n b_{1j} x_j, \sum_{j=1}^n b_{2j} x_j\right).$$

Problem 5 (Axler 3A6) If V, W, Y, and Z are four vector spaces over the same field and

 $L \in \mathcal{L}(V, W), \ M \in \mathcal{L}(W, Y), \ and \ T \in \mathcal{L}(Y, Z),$

recall that the **compositions** $M \circ L$ and $T \circ M$ are defined by

$$M \circ L(v) = M(V(v))$$
 and $T \circ M(w) = T(M(w)).$

- (a) Show that $M \circ L \in \mathcal{L}(V \to Y)$ and $T \circ M \in \mathcal{L}(W \to Z)$.
- (b) To what sets do $(T \circ M) \circ L$ and $T \circ (M \circ L)$ belong?

(c) Show

$$(T \circ M) \circ L = T \circ (M \circ L).$$

Problem 6 Given any vector space V, show that the **identity** function $id_V : V \to V$ by

$$\operatorname{id}_V(v) = v$$

satisfies $\operatorname{id}_V \in \mathcal{L}(V \to V)$.

Problem 7 (Axler 3A8) Give an example of a function $f : \mathbb{R}^2 \to \mathbb{R}$ satisfying f(av) = af(v) for every $a \in \mathbb{R}$ and $v \in \mathbb{R}^2$, but

$$f \notin \mathcal{L}(\mathbb{R}^2 \to \mathbb{R}).$$

Problem 8 (Axler 3A10) Let W be a **proper** subspace of a vector space V. (This just means W is a subspace of V, but $W \neq V$.) Also, let Z be a vector space over the same field, and let $L \in \mathcal{L}(W \to Z)$. Define

$$f: V \to Z$$
 by $f(v) = \begin{cases} Lv, & \text{if } v \in W \\ \mathbf{0}, & \text{if } v \notin W. \end{cases}$

If there is some $v_1 \in W$ such that $Lv_1 \neq \mathbf{0}$, then show $f \notin \mathcal{L}(V \to Z)$.

Problem 9 (Axler 3A11) Let V be a two-dimensional subspace of \mathbb{R}^3 and assume $L \in \mathcal{L}(V \to W)$. Show there exists a linear function $T \in \mathcal{L}(\mathbb{R}^3 \to W)$ with

$$T(v) = L(v)$$
 for every $v \in V$.

Problem 10 (Axler 3A14) Find linear functions $L, T \in \mathcal{L}(\mathbb{R}^2 \to \mathbb{R}^2)$ for which

$$L \circ T \neq T \circ L.$$

Remember that in this case $T \circ L$ and $L \circ T$ are in $\mathcal{L}(\mathbb{R}^2 \to \mathbb{R}^2$ and we call these compositions **products** and write $TL = T \circ L$ and $LT = L \circ T$. Thus, the "product" is not commutative in the ring $\mathcal{L}(\mathbb{R}^2 \to \mathbb{R}^2)$.